

# Conformal Prediction for Surrogate Modeling with Gaussian Processes

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# Problem formulation

- ▶ Computer code  $g : \mathcal{X} \rightarrow \mathcal{Y}$ , with  $\mathcal{X}, \mathcal{Y}$  measurable spaces, used in industry applications
- ▶ Uncertainty Quantification (UQ) methodology: how uncertainty on the inputs  $X$  affects our knowledge of the output  $g(X)$ ?

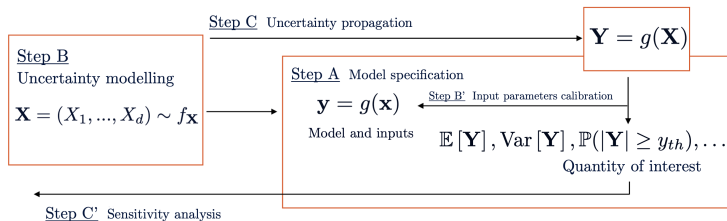
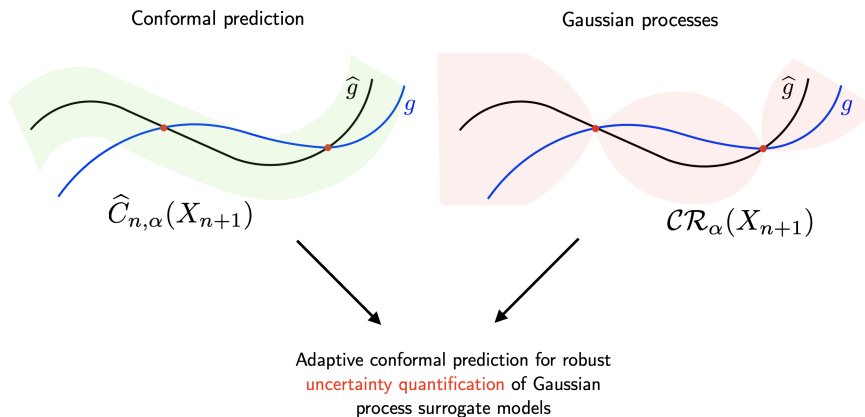


Figure: General UQ methodology [De Rocquigny et al., 2008].

# Problem formulation

- ▶ Some codes are time-costly → use of *surrogates*  $\hat{g}$
- ▶ Surrogates (or metamodels) facilitate heavy Monte Carlo batch runs and/or sensitivity analysis → in *Step C*,  $C'$
- ▶ Assess the *quality* of these surrogates (decision making, trust in simulation outputs, ...) → metamodel *validation*
- ▶ Metamodel validation is still a debated topic and has open questions → no consensus on a best methodology
- ▶ Gaussian Processes (GPs) are a type of Bayesian metamodels → with a notion of *uncertainty* → but needs hypotheses to be interpreted
- ▶ Idea: use **Conformal Prediction** (CP) paradigm [Vovk et al., 2005] which is a generic, model-agnostic theory allowing to build *prediction sets* with frequentist coverage guarantees.
- ▶ Possibly useful for *qualifying* GP surrogate models?

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# CP in regression setting

Let  $(\Omega, \mathcal{F}, \mathbb{P})$  be a probability space.

## Definition

[Vovk et al., 2005] Let  $\mathcal{Z} := \mathcal{X} \times \mathcal{Y}$ . Let  $n \in \mathbb{N}$  and  $\mathcal{D}_n = \{Z_1, \dots, Z_n\} \in \mathcal{Z}^n$  a training sample. For  $\alpha \in (0, 1)$ , a conformal predictor of coverage  $1 - \alpha$  is any measurable function of the form:

$$\begin{aligned} C_\alpha: \mathcal{Z}^n \times \mathcal{X} &\rightarrow 2^{\mathcal{Y}} \\ (\mathcal{D}_n, X) &\mapsto C_{n,\alpha}(X), \end{aligned} \tag{1}$$

s.t. for any new couple of points  $Z_{n+1} = (X_{n+1}, Y_{n+1}) \in \mathcal{Z}$  (**marginal coverage property**):

$$\mathbb{P}(Y_{n+1} \in C_{n,\alpha}(X_{n+1})) \geq 1 - \alpha. \tag{2}$$

Three main methods for estimating conformal-predictors: full-conformal, split-conformal (see [Angelopoulos and Bates, 2023]) and **cross conformal** estimators  $\rightarrow$  focus on the latter



# Jackknife+/minmax interval estimators

- ▶  $g : \mathcal{X} \subseteq \mathbb{R}^d \rightarrow \mathcal{Y} \subseteq \mathbb{R}$
- ▶  $\mathcal{D}_n = \{(X_1, g(X_1)), \dots, (X_n, g(X_n))\}$  an i.i.d. design of experiments
- ▶  $\hat{g}$  a surrogate model trained on  $\mathcal{D}_n$ ,  $\hat{g}_{-i}$  leave-one-out (LOO) surrogate model trained on  $\mathcal{D}_n \setminus \{(X_i, g(X_i))\}$
- ▶ With empirical quantile of LOO residues  $\rightarrow$  can build interval estimators: Jackknife+  $\hat{C}_{n,\alpha}^{J+}$  & Jackknife-minmax  $\hat{C}_{n,\alpha}^{J-minmax}$

Estimators	$\hat{C}_{n,\alpha}^{J+}$	$\hat{C}_{n,\alpha}^{J-minmax}$
Marginal coverage	$\alpha \in (0, 1/2)$	$\alpha \in (0, 1)$
+	Cross-validation method	Coverage property
	Fast to compute	
-	Constant width	Width is too large

Table: Main cross-conformal estimators pros and cons.

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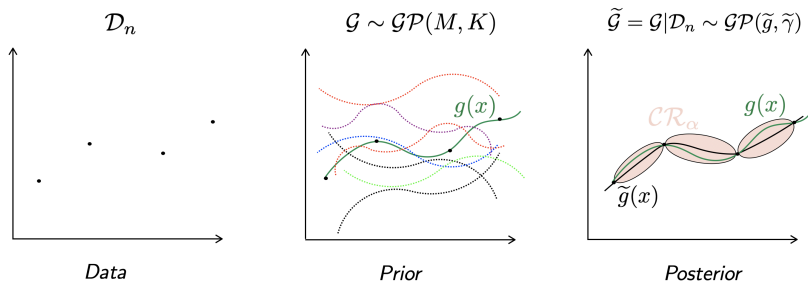
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# Gaussian process (GP) surrogates



- ▶ GP metamodel prediction is the *posterior mean*  $\hat{g} = \tilde{g}$ .
- ▶ Notion of uncertainty through the posterior covariance  $\tilde{\gamma}$  and the Gaussian structure of the metamodel.

# Bayesian credibility intervals

- ▶ Credibility intervals of the posterior GP, for any new point  $X_{n+1} \in \mathcal{X}$ ,  $\alpha \in (0, 1)$ :

$$\mathcal{CR}_\alpha(X_{n+1}) = \left[ \tilde{g}(X_{n+1}) \pm u_{1-\alpha/2} \tilde{\gamma}(X_{n+1}) \right]. \quad (3)$$

- ▶ Has the **conditional coverage property** (stronger than marginal):

$$\mathbb{P}(g(X_{n+1}) \in \mathcal{CR}_\alpha(X_{n+1}) \mid \mathcal{D}_n) = 1 - \alpha. \quad (4)$$

- ▶ *However*, the above equality relies on **two** hypotheses:
  1.  $g$  is **modeled** by  $\mathcal{G} \sim \mathcal{GP}(M, K)$
  2. priors mean and covariance functions  $M, K$  are **well-specified**.
- ▶ No generic way to test these two hypotheses when metamodeling black-box computer codes  $\rightarrow$  *a real challenge for industrial application of UQ.*

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# The proposed J+GP estimator

- ▶ Optimize the hyperparameters of the GP kernel.
- ▶ Posterior mean  $\tilde{g}$  and standard-deviation  $\tilde{\gamma} = \tilde{K}^{1/2}$ .
- ▶ Define the Leave-One-Out-Gaussian ( $\text{LOO}\gamma$ ) error:

$$R_i^{\text{LOO}\gamma} := \frac{|g(X_i) - \tilde{g}_{-i}(X_i)|}{\tilde{\gamma}_{-i}^\beta(X_i)}, \forall \beta \in \mathbb{N}. \quad (5)$$

## Main result and consequences [Jaber et al., 2024a]

$$\hat{C}_{n,\alpha}^{\text{J+GP}}(X_{n+1}) = \left[ \hat{q}_{n,\alpha}^{\pm} \left\{ \tilde{g}_{-i}(X_{n+1}) \pm R_i^{\text{LOO}\gamma} \times \tilde{\gamma}_{-i}^\beta(X_{n+1}) \right\} \right] \quad (6)$$

- ▶ Coverage property **still verified** for  $\alpha \in (0, 1/2)$
- ▶ Intervals have adaptive width  $\rightarrow$  **more informative**
- ▶ **No hypotheses** for interpreting the interval!
- ▶ The J+GP-minmax variant **has the same properties**

# Proposed methodology for GP qualification

On a test-set  $\mathcal{D}_m \neq \mathcal{D}_n$ : compare different GPs as well as classical cross-CP and Bayesian credibility sets by computing:

- ▶ the predictivity coefficient:

$$Q^2 = 1 - \sum_{i=1}^m \frac{|g(X_i) - \tilde{g}(X_i)|^2}{\text{Var}(g(X_i))}. \quad (7)$$

- ▶ the empirical coverage for usual  $\alpha$  thresholds (1%, 5%, 10%):

$$\frac{1}{m} \sum_{i=1}^m \mathbb{1} \left\{ g(X_i) \in \hat{C}_{n,\alpha}^*(X_i) \right\} \gtrsim 1 - \alpha.$$

- ▶ the adaptivity, by use of the Spearman correlation coefficient  $r_s$  between the width of the interval and the metamodel error:

$$0 \ll r_s \left( \left\{ (\ell(\hat{C}_{n,\alpha}^*(X_i)), |g(X_i) - \tilde{g}(X_i)|) \right\}_{i \in \{1, \dots, m\}} \right)$$

## Industrial use case

- ▶ The **steam generator (SG)** → heat exchanger between the primary and secondary circuits of a nuclear power plant (NPP).

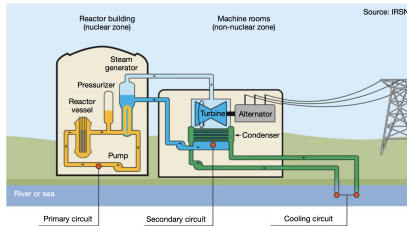


Figure: NPP Scheme

- ▶ Corrosion in the secondary circuit produces iron oxide impurities → **clogging** of the SG over time, requires **maintenance**.



Figure: video examination during an PWR outage (© EDF)



## Industrial use case

- ▶ EDF *time-costly* steam-generator clogging simulation code [Jaber et al., 2024b], input dimension  $d = 7 \rightarrow$  GP metamodel with Matérn- $\nu$  covariance priors, with hyperparameters optimized  $(\sigma, \theta)$  by MLE:

$$K(x, x') = \sigma^2 \frac{2^{1-\nu}}{\Gamma(\nu)} \left( \sqrt{2\nu} \frac{|x - x'|}{\theta} \right)^\nu K_\nu \left( \sqrt{2\nu} \frac{|x - x'|}{\theta} \right).$$

- ▶ Parameter  $\nu$  governs the *regularity* of the metamodel
- ▶ Crude Monte Carlo design of experiments of  $10^3$  points, 80% used for training and 20% for testing/qualification.

Component	Distribution	Component	Distribution
$x^{(1)}$	$\mathcal{N}(101.6, 4.0)$	$x^{(5)}$	$\mathcal{T}(0.5, 5.0, 10.0) \times 10^{-6}$
$x^{(2)}$	$\mathcal{N}(0.0233, 0.0005)$	$x^{(6)}$	$\mathcal{T}(1.0, 4.5, 8.0) \times 10^{-9}$
$x^{(3)}$	$\mathcal{T}(0.2, 0.3, 0.5)$	$x^{(7)}$	$\mathcal{T}(0.1, 7.8, 12) \times 10^{-4}$
$x^{(4)}$	$\mathcal{T}(0.01, 0.05, 0.3)$		

**Table:** Distributions of the input components of the clogging code.

*How to quantify the quality of the GP-surrogate in prevision?*

$\rightarrow$  UQ with adaptive conformal predictors!

# Average widths / correlation, $\alpha = 0.05$ , $\beta = 1/2$

✓ / ✗: empirical coverage is / is not achieved.

$\nu$	$Q^2$	$CR_\alpha$	$\widehat{C}_{n,\alpha}^{J-mm}$	$\widehat{C}_{n,\alpha}^{J-mm-GP}$
1/2	0.990	5.6 ✓	3.9 ✗	3.7 ✗
3/2	0.996	2.4 ✓	2.3 ✗	2.3 ✓
5/2	0.997	1.9 ✗	2.2 ✓	2.1 ✓

Table: Average widths of prediction intervals and  $Q^2$ .

$\nu$	$Q^2$	$CR_\alpha$	$\widehat{C}_{n,\alpha}^{J-mm}$	$\widehat{C}_{n,\alpha}^{J-mm-GP}$
1/2	0.990	0.46 ✓	0.66 ✗	0.63 ✗
3/2	0.996	0.35 ✓	0.65 ✗	0.55 ✓
5/2	0.997	0.21 ✗	0.60 ✓	0.45 ✓

Table: Correlation between widths and GP approximation error and  $Q^2$ .

→ A more robust validation of the Matérn-5/2 GP prior!

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# The Jackknife+ estimator

- ▶  $g : \mathcal{X} \subseteq \mathbb{R}^d \rightarrow \mathcal{Y} \subseteq \mathbb{R}$
- ▶  $\mathcal{D}_n = \{(X_1, g(X_1)), \dots, (X_n, g(X_n))\}$  an i.i.d. design of experiments,  $X_{n+1}$  a new point
- ▶  $\hat{g}$  a surrogate model trained on  $\mathcal{D}_n$ ,  $\hat{g}_{-i}$  trained on  $\mathcal{D}_n \setminus \{(X_i, g(X_i))\}$ , and  $\hat{q}_{n,\alpha}^\pm(\cdot)$  empirical  $\alpha$ -quantile
- ▶ Leave-One-Out (LOO) error:  $R_i^{LOO} := |g(X_i) - \hat{g}_{-i}(X_i)|$

## Definition

[Barber et al., 2021] The Jackknife+ estimator is given by:

$$\hat{C}_{n,\alpha}^{J+}(X_{n+1}) = \left[ \hat{q}_{n,\alpha}^\pm \left\{ \hat{g}_{-i}(X_{n+1}) \pm R_i^{LOO} \right\} \right]$$

- ▶ Coverage property verified only for  $\alpha \in (0, 1/2)$
- ▶ Intervals have almost constant width for all points (including training points)  $\rightarrow$  **not that informative**

# Jackknife-minmax

- ▶ [Barber et al., 2021] Replace metamodel prediction with minimum (resp. maximum) of LOO error:

$$\hat{C}_{n,\alpha}^{J-mm}(X_{n+1}) = \left[ \begin{array}{l} \min_{i=1,\dots,n} \{ \hat{g}_{-i}(X_{n+1}) \} - \hat{q}_{n,\alpha}^- \{ R_i^{LOO} \}, \\ \max_{i=1,\dots,n} \{ \hat{g}_{-i}(X_{n+1}) \} + \hat{q}_{n,\alpha}^+ \{ R_i^{LOO} \} \end{array} \right]. \quad (8)$$

- ▶ Prediction intervals  $\rightarrow$  not centered anymore but have *marginal coverage guarantee*:

$$\forall \alpha \in (0, 1), \quad \mathbb{P} \left( g(X_{n+1}) \in \hat{C}_{n,\alpha}^{J-mm}(X_{n+1}) \right) \geq 1 - \alpha. \quad (9)$$

- ▶ The resulting intervals will be more *conservative* i.e. with larger width.

# Cross conformal predictors summary

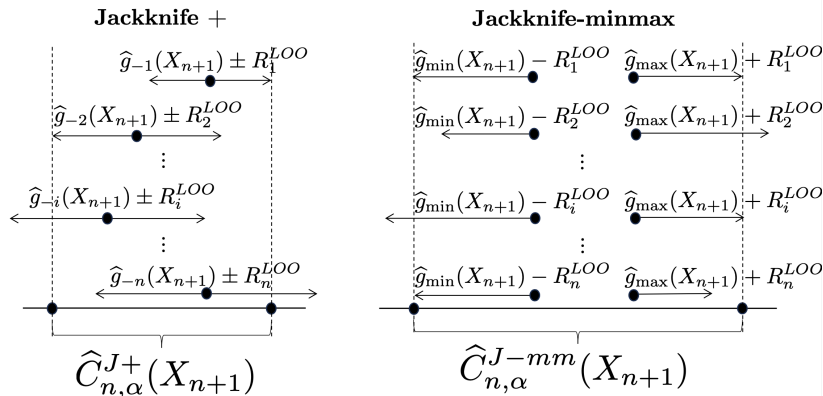


Figure: Jackknife+, and Jackknife-minmax schemes, adapted from [Barber et al., 2021].



# The Burnaev-Wasserman program

[Burnaev and Vovk, 2014] Assume that  $\mathcal{X} \subset \mathbb{R}^d$ , for all  $i$ ,  $X_i \in L^2(\Omega)$  and the model  $g$  is truly Gaussian. The credibility sets have exact coverage and output an interval of the form :

$$\mathcal{C}\mathcal{R}_\alpha(X_{n+1}) = [B_*, B^*]. \quad (10)$$

The CRR method with the GP rule outputs a prediction interval of the form:

$$\widehat{\mathcal{C}}_{n,\alpha}^{CRR}(X_{n+1}) = [C_*, C^*]. \quad (11)$$

A natural question is to compare the differences of the bounds of these two intervals and their asymptotic behaviour

## An asymptotic result

See [Burnaev and Vovk, 2014] for a proof of the following.

### Theorem

*Under the previous assumptions, we get:*

$$\sqrt{n}(B^* - C^*) \xrightarrow[n \rightarrow \infty]{Law} \mathcal{N}(0, h(\alpha)), \quad (12)$$

*and similarly for the lower-bound.*

Here  $h$  is a function of the  $(1 - \alpha/2)$ -quantile of the standard normal distribution and of the mean and variance of the input distribution.

# CPU dataset, $\alpha = 0.1$ , $\beta = 1/2$

✓ / ✗: empirical coverage is / is not achieved.

$\nu$	$Q^2$	$\mathcal{CR}_\alpha$	$\widehat{C}_{n,\alpha}^{J+GP}$	$\widehat{C}_{n,\alpha}^{J-mm-GP}$
1/2	0.845	91.6 ✓	28.14 ✓	47.3 ✓
3/2	0.856	72.9 ✓	29.9 ✓	47.1 ✓
5/2	0.854	70.9 ✓	32.1 ✓	49.0 ✓

Table: Average widths of prediction intervals and  $Q^2$ .

$\nu$	$Q^2$	$\mathcal{CR}_\alpha$	$\widehat{C}_{n,\alpha}^{J+GP}$	$\widehat{C}_{n,\alpha}^{J-mm-GP}$
1/2	0.845	0.720 ✓	0.627 ✓	0.782 ✓
3/2	0.856	0.492 ✓	0.485 ✓	0.470 ✓
5/2	0.854	0.626 ✓	0.533 ✓	0.543 ✓

Table: Correlation between widths and GP approximation error and  $Q^2$ .

→ The metamodel with the lowest  $Q^2$  is more robust to uncertainty!

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